Sensing and imaging systems can provide a number of capabilities required for anticipated NASA missions including exploration of Mars and the Moon. Capabilities of interest include the following:

- **Orbiting sensors to map:**
  - Extent and concentration of useful, surface, or subsurface resources to identify promising outpost or science sites and traversable terrains;
  - Surface topography and roughness to identify promising safe landing sites for human, robotic science, and pre-provisioning missions, and to guide pinpoint landing algorithms.

- **Robot-mounted sensors for:** estimating robot pose and motion; recovering 3D scene structure; identifying hazards or objects of interest; identifying articulation of observed objects, and performing visual serving.  
  Flight ready (radiation and temperature hardened), high cycle rate, and low power systems are generally preferred. Applications include:
  - Autonomous rendezvous and docking;
  - Pinpoint landing;
  - Surface navigation;
  - Surface and on-orbit assembly/construction;
  - Resource mining/processing;
  - Multi-vehicle cooperation.

Specific technologies of interest in addressing these challenges include:
• Rapid frame rate arrays for 1, 1.5 and 2 \( \mu \text{m} \) vision (2D and 3D);
• Multi-wavelength laser arrays;
• Flight-ready, high-speed, medium-resolution (640x480) stereo-vision sensors;
• Flight-ready, low-power lighting systems (headlights) to allow imaging during nighttime robotic operations;
• Tightly coupled inertial and vision sensors for pose estimation;
• Ground truthing systems for evaluating performance of ranging systems.

A number of related technologies are of interest but are covered under other subtopics, including:

• High power or high rep-rate lasers (S6.02, S1.04);
• Ultra-high sensitivity detectors and arrays (S4.01);
• Active and passive microwave sensors (S6.04, S6.05).